Shape Analysis for Redistricting modern geometry meets modern politics

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This is joint work with...

Total Variation Isoperimetric Profiles

https://arxiv.org/abs/1809.07943

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Graph Laplacians

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Discrete Compactness

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Curve-Shortening Flow

https://zachschutzman.com/distflow

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WHAT IS COMPACTNESS?



Vaguely, it's supposed to describe the niceness of the shape of a district.

Compactness is in the discourse

Dy Christopher Instah

America's most gerrymandered congressional districts

Michigan has districts in shapes that even a flexible

salamander would be incapable of contorting itself into. To be sure, there are perfectly

legitimate rea Democratic-le

Ohio's wonky districts



Compactness is in the law

Legislative Apportionment Commission shall attempt to form functionally contiguous and compact territories. For purposes of this section, a

lowa law provides that congressional and legislative districts should be reasonably compact in form. As noted previously, the requirement to establish

> (i) Each congressional district shall consist of areas of convenient territory contiguous by land. Areas that meet only at points of adjoining corners are not contiguous.

Compactness is poorly defined

contiguous and compact territories. For purposes of this section, a "functionally contiguous and compact territory" is one that facilitates representation by minimizing impediments to travel within the district.

In order to compare the relative compactness of two or more districts or of two or more alternative redistricting plans, the Code provides that two measures of compactness, length-width compactness⁷⁴ and perimeter compactness, ⁷⁵ shall be used.

(vii) Compactness shall be determined by circumscribing each district within a circle of minimum radius and measuring the area, not part of the Great Lakes and not part of another state, inside the circle but not inside the district. The measures are basic Polsby-Popper

$$0 < \mathsf{PP}(\Omega) = rac{4\pi \cdot \mathsf{Area}(\Omega)}{\mathsf{Perim}^2(\Omega)} \leq 1$$

The measures are basic Polsby-Popper

scale-free

loves circles

isoperimetricky





The measures are basic Bounding regions

$$f(\Omega) = rac{\mathsf{Area}(\Omega)}{\mathsf{Area}(\mathcal{B}(\Omega))}$$

The measures are basic Bounding regions

. . .

B can be Circle [Reock] Square [Square Reock] Convex hull [Convex hull] Ellipse, rectangle Axis-aligned ellipse, rectangle The measures are basic Bounding regions

> scale-free not sensitive at boundary

inconsistent good interpretation?



The measures are basic Miscellany

Largest inscribed circle

Just the perimeter

Longest axis by greatest orthogonal width

Population-weighted versions

Reciprocal of Polsby-Popper

What's the Takeaway?

The geometry is important, and a lot of geometry has been done in the last 2000 years. So, let's use it. But, maybe we should care a little less.

This talk:

The case for multiscale methods 'Continuous' definitions Isoperimetric profiles/total variation Curve-shortening flow 'Discrete' definitions Constructing a dual graph Discrete analogues Graph spectrum Discrete curvature? You should ask me questions

What's the dream?

Computable: we

should have a good algorithm to find the measure **Informative:** the score should say something about the geometry

Stable: similar shapes should have similar scores

Explainable: it should be easy to tell someone what's going on

CONTINUOUS METHODS

Isoperimetric profiles

"Total Variation Isoperimetric Profiles" (2018), DeFord, Lavenant, Schutzman, & Solomon

"For all times $t \in (0, 1]$, what is the smallest perimeter of any inscribed subregion of Ω which fills a *t*-fraction of the area?"

Gives you a function or a curve or a vector from your shape.

What's so cool about it?

t = 1 recovers the Polsby-Popper score Some basic algebra lets you get the largest inscribed circle Stable under perturbations The function and its derivative tell you some stuff about the shape at different resolutions

Formalization

$$\mathsf{TV}[f] = \int_{\mathbb{R}^n} \|\nabla f\|_2 \, dx.$$

$$\operatorname{area}(\partial \Sigma) = \mathsf{TV}[\mathbb{1}_{\Sigma}].$$

$$I_{\Omega}(t) = \left\{egin{array}{ccc} \inf_{f\in L^1(\mathbb{R}^n)} & \mathsf{TV}[f] \ \mathsf{subject to} & \int_{\mathbb{R}^n} f(x) \mathrm{d}x = t \ & 0 \leq f \leq \mathbb{1}_{\Omega} \ & f(x) \in \{ \ 0,1 \ \} \ orall x \in \mathbb{R}^n. \end{array}
ight.$$

$$I_{\Omega}(t) = \begin{cases} \inf_{f \in L^{1}(\mathbb{R}^{n})} & \mathsf{TV}[f] \\ \text{subject to} & \int_{\mathbb{R}^{n}} f(x) dx = t \\ & 0 \leq f \leq \mathbb{1}_{\Omega} \\ & f(x) \in \{ 0, 1 \} \ \forall x \in \mathbb{R}^{n}. \end{cases}$$

$$I_{\Omega}(t) = \left\{egin{array}{ccc} \inf_{f\in L^1(\mathbb{R}^n)} & \mathsf{TV}[f] \ \mathsf{subject to} & \int_{\mathbb{R}^n} f(x) \mathrm{d}x = t \ & 0 \leq f \leq \mathbb{1}_{\Omega} \ & f(x) \in \& [0,1] \& \ orall x \in \mathbb{R}^n. \end{array}
ight.$$

$$I_{\Omega}(t) = \begin{cases} \inf_{f \in L^{1}(\mathbb{R}^{n})} & \mathsf{TV}[f] \\ \text{subject to} & \underbrace{\int_{\mathbb{R}^{n}} f(x) dx = t}_{0 \le f \le \mathbb{1}_{\Omega}} \\ f(x) \in [0, 1] \quad \forall x \in \mathbb{R}^{n}. \end{cases}$$

$$I_{\Omega}(t) = \begin{cases} \inf_{f \in L^{1}(\mathbb{R}^{n})} & \mathsf{TV}[f] \\ \text{subject to} & \int_{\mathbb{R}^{n}} f(x) dx = t \\ & 0 \leq f \leq \mathbb{1}_{\Omega} \end{cases}$$

Using some duality arguments, we show that this is the *lower convex envelope* of the Isoperimetric profile. (See the paper)





	District 1	District 2	District 3	District 4	District 5	District 6	District 7	District 8	District 9	District 10	District 11	District 12	District 13
t = 0.12		ć										3	-
t = 0.23		Ś.										٢	
t = 0.34		\$							•			~	-
t = 0.45		٢				•			*			~	-
t = 0.56		¢,	-			-			•			^م م	-
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t = 1.0	Ň	Ъ,	i de la constante de la consta		ŧ	4	4	*	*	*	_	Jone	77



Nice properties

satisfies three of our desiderata

good algorithms to compute

we can make it measure-aware

isoperimetricky

An Open Problem

Open Problem

The TV relaxation works in \mathbb{R}^n (examples of \mathbb{R}^3 in the paper) and should work over any metric space where all the calculus stuff makes sense.

Is there a good algorithm to compute the isoperimetric profile in \mathbb{R}^2 ?

Curve-shortening flow

take a (closed) smooth curve in the plane

at each time step, at each point:

(1) find the curvature κ

(2) move a distance proportional to κ ...

... in the direction normal to the tangent

(3) rescale the area

Curve-shortening flow

the perimeter shrinks becomes a circle in finite time



Record the PP score at each time This assigns a function to a shape

What's so cool about it?

t = 0 recovers the Polsby-Popper score monotonically decreasing in tdiscretizes nicely satisfies all four desiderata The function and its derivative tell you some stuff about the shape at different resolutions

http://zachschutzman.com/distflow



Nice properties

satisfies our desiderata

easy to compute

discretizes nicely

isoperimetricky

DISCRETE METHODS

Constructing the dual graph



the districts are subgraphs we can talk about 'boundary' and 'interior' nodes there's a natural metric to use discrete polsby-popper discrete convex hull

A quick illustration



Graphic adapted from Duchin & Tenner

What's the up side?

dual graphs have structure! the sensitivity issue largely goes away no longer depends on the \mathbb{R}^2 embedding

But, we know how to do more with graphs than just count vertices!

Take a graph. Define the Laplacian \mathcal{L} as the matrix with -1 in entry *ij* if edge *ij* is in the graph and deg(*i*) in entry *ii*. Zeros elsewhere.

This matrix is real and symmetric, so it's positive semi-definite Let's consider its eigenvalues.

Laplacians

$\mathcal{L}_{S} = \begin{bmatrix} & \cdots & \\ \vdots & \ddots & \vdots \\ & \cdots & \end{bmatrix} \quad \mathcal{L}_{P} = \begin{bmatrix} [\mathcal{L}_{d_{1}}] & \cdots & \mathbf{0} \\ \vdots & \ddots & \vdots \\ \mathbf{0} & \cdots & [\mathcal{L}_{d_{n}}] \end{bmatrix}$

 \mathcal{L}_P is \mathcal{L}_S with some edges deleted.

These two matrices 'know' almost all of the discrete geometry of a districting plan.

Laplace spectrum: small eigenvalues

There's a zero eigenvalue for each connected component The second eigenvalue is no more than the vertex connectivity

Moral truth: the *k*th eigenvalue says something about how easy it is to cut the graph into *k* pieces.

Laplace spectrum: large eigenvalues

The largest eigenvalue is less than the max degree Summing in reverse, the degree sequence majorizes the eigenvalues Kirchoff's Matrix-Tree Theorem

Laplacians - Current work help us do our research!

Summing eigenvalues correlates very strongly with geometric compactness measures. Why?

- Do these have any meaning as operators?
- Is there meaning to the Laplace eigenvectors?

THANK YOU!